

# The Core of Approval-Based Committee Elections with Few Seats

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## Abstract

In an approval-based committee election, the goal is to select a committee consisting of  $k$  out of  $m$  candidates, based on  $n$  voters who each approve an arbitrary number of the candidates. The *core* of such an election consists of all committees that satisfy a certain stability property which implies proportional representation. In particular, committees in the core cannot be “objected to” by a coalition of voters who is underrepresented. The notion of the core was proposed in 2016, but it has remained an open problem whether it is always non-empty. We prove that core committees always exist when  $k \leq 8$ , for any number of candidates  $m$  and any number of voters  $n$ , by showing that the Proportional Approval Voting (PAV) rule due to [Thiele \(1895\)](#) always satisfies the core when  $k \leq 7$  and always selects at least one committee in the core when  $k = 8$ . We also develop an artificial rule based on recursive application of PAV, and use it to show that the core is non-empty whenever there are  $m \leq 15$  candidates, for any committee size  $k \leq m$  and any number of voters  $n$ . These results are obtained with the help of computer search using linear programs.

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# 1 Introduction

The seminal work of Aziz et al. (2016, 2017) introduced a rigorous way of reasoning about voter representation in multi-winner elections. Their model considers *approval-based committee elections*, where the task is to identify a committee  $W \subseteq C$  of  $k$  out of  $m$  candidates, based on a set of voters  $N$ , with each  $i \in N$  indicating a subset  $A_i \subseteq C$  of candidates that  $i$  approves. Aziz et al. (2016, 2017) formulated a compelling axiom called Extended Justified Representation (EJR) which gives representation guarantees to every group of voters who approve sufficiently many candidates in common. Researchers discovered that voting rules developed 130 years ago by Thiele (1895) and Phragmén (1894) satisfy this or related axioms (Brill et al., 2023; Aziz et al., 2017; Janson, 2016). Interesting *new* rules satisfying EJR have recently been developed (Aziz et al., 2018; Peters and Skowron, 2020; Brill and Peters, 2023), with one of them (the “Method of Equal Shares”) now in active use for the participatory budgets in several cities in Poland, Switzerland, and the Netherlands.

Aziz et al. (2016, 2017, Section 5.2) also defined another representation axiom that is significantly stronger than EJR, called *core stability* in analogy to a similar concept from cooperative game theory. A committee  $W$  is core stable if for every set  $T \subseteq C$ , there are not too many voters who prefer the set  $T$  to  $W$ , namely we have

$$|\{i \in N : |A_i \cap T| > |A_i \cap W|\}| < |T| \cdot \frac{n}{k}.$$

If this inequality were violated for some  $T$ , then the set of voters on the left-hand side could form a *blocking coalition* of a size that is large enough for the coalition to “deserve” to decide to include  $T$  in the committee.

The EJR property is weaker than core stability (because under EJR voters are only allowed to join the blocking coalition if they approve all the candidates in  $T$ , i.e.,  $|A_i \cap T| = |T|$ ), but in exchange there are several attractive voting rules satisfying EJR. On the other hand, Aziz et al. (2016, 2017) noted that “the core stability condition appears to be too demanding, as none of the voting rules considered in our work is guaranteed to produce a core stable outcome”. No such voting rules have been discovered since. They conclude: “It remains an open question whether the core [is always] non-empty.” This question remains open more than 8 years later.

Some amount of progress has been made, and in particular it is known that there always exist committees satisfying approximate variants of the core (Peters and Skowron, 2020; Jiang et al., 2020; Munagala et al., 2022b), and the core exists on single-peaked approval profiles (Pierczyński and Skowron, 2022) and on profiles where each candidate has at least  $k$  copies (Brill et al., 2022).

To the best of my knowledge, the only known existence result that holds *in general* is that the core is non-empty for  $k = 3$ , which Cheng et al. (2020, Section 3.1) showed by case analysis. Cheng et al. (2020) conclude that a “major open question is the existence of deterministic stable committees in the Approval Set setting, generalizing our positive result for  $k = 3$  to general  $k$ . We conjecture that such a stable committee always exists. Via computer-assisted search, we have shown that this conjecture holds for small numbers of voters and candidates ( $m + n \leq 14$ ).”

It might seem surprising that the state of the art has not improved beyond these very small parameter values. In particular, there is a natural way of using mixed integer linear programming (ILPs) to search for counterexamples to core existence: fix  $m$  and  $k$ , and introduce a fractional variable for each possible ballot, indicating what fraction of the voters submit this ballot. Then, for every possible committee, enforce using binary variables that there exists at least one successful core deviation. If an ILP solver determines that the resulting program is infeasible, this implies the non-emptiness of the core for  $m$  and  $k$ , for any number  $n$  of voters. Unfortunately, the size of this program grows rapidly, and they are not easy to solve even for very small sizes (Gurobi solves  $m = 7$ ,  $k = 5$ , in 450s, but did not solve  $m = 7$ ,  $k = 4$  after 134 000s (37h) on 8 cores).<sup>1</sup>

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<sup>1</sup>The same problem can also be encoded as an SMT problem on linear arithmetic. This can sometimes lead to

In this paper, by deriving a new way of using solvers, we show that the core always exists for committee sizes up to  $k = 8$ , regardless of the number of candidates (improving upon the previous result for  $k = 3$ ). We also show that the core always exists when the number  $m$  of candidates is at most 15, for any  $k \leq m$ . Both results hold for any number  $n$  of voters.

These results are obtained by analyzing variants of *Proportional Approval Voting* (PAV), the voting rule proposed by Thiele (1895). This voting rule works by maximizing a carefully chosen objective function over the set of all committees of size  $k$ . We show via linear programs that PAV always selects a core-stable committee when  $k \leq 7$ , and that it always selects at least one core-stable committee when  $k = 8$ , perhaps tied with other committees that fail core-stability. This performance of the PAV rule is remarkable, and contrasts with other rules such as the Phragmén rule and the Method of Equal Shares which fail the core for  $k = 6$  and  $k = 7$ , respectively (see Footnote 3). In many applications, the number of seats to fill will be 8 or fewer, and thus our result suggests that PAV is a good rule for such contexts.<sup>2</sup>

For the results about limited numbers of candidates, we consider a recursive version of PAV where, if the PAV committee fails the core because some set  $T$  has too much support, we then re-compute PAV subject to the constraint that  $T \subseteq W$  and without taking into account the voters who were part of the blocking coalition. If the result still fails core-stability, we add additional constraints. We show that if  $m \leq 15$ , this process always terminates with a core-stable committee. However, there are examples where the rule fails to guarantee the core for  $m = 16$ .

As mentioned, these results were obtained with the help of linear programming. This becomes feasible even for these quite large sizes because we can fix *one* committee, and add constraints that this committee is the one selected by the voting rule under consideration. This is much simpler than a program that needs constraints for all possible committees. Linear programming has been used before to analyze sequential versions of PAV (Skowron, 2021; Sánchez-Fernández et al., 2017). The infeasibility of the relevant programs can be compactly certified via Farkas’ lemma, allowing efficient verification of our results without having to trust a solver. Code for these tasks is available at <https://github.com/DominikPeters/core-few-candidates/>.

## 2 Related Work

**Barriers to core existence.** Proving that the core is non-empty is difficult because several natural strategies are known not to work. Importantly, all known voting rules that satisfy weakenings of the core such as EJRs fail the core, including the PAV rule (Aziz et al., 2017, Example 6, Peters and Skowron, 2020, Section 1). Peters and Skowron (2020, Theorem 10) show that every welfarist rule (one that depends only on voter utilities) must fail the core. They also show that every voting rule satisfying the Pigou–Dalton principle (which says that outcomes that induce a more equitable social welfare distribution should be preferred; this is satisfied by PAV) cannot satisfy the core, and indeed cannot provide better than a 2-approximation to it (Peters and Skowron, 2020, Theorem 5).

**Computational complexity.** It is NP-hard to compute the PAV rule (Aziz et al., 2015, Corollary 1), but it is fixed-parameter tractable for a variety of parameters (Yang and Wang, 2023). A local search variant of PAV retains its proportionality properties and can be computed in polynomial time (Aziz et al., 2018) for an appropriately chosen tolerance parameter (Kraiczky and Elkind, 2024). The problem of checking whether a given committee is in the core is coNP-complete (Brill

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faster solve times, but it is also only feasible for very small sizes.

<sup>2</sup>Note, however, that even for  $k = 6$ , PAV may select committees that fail laminar proportionality (Peters and Skowron, 2020) and are intuitively unfair. A three-voter example for  $k = 6$  is  $A_1 = \{c_1, c_2, c_3\}$ ,  $A_2 = \{c_1, c_2, c_4\}$ , and  $A_3 = \{c_5, c_6, c_7\}$  where  $W = \{c_1, c_2, c_3, c_5, c_6, c_7\}$  is a global PAV committee (tied with others) while laminar proportionality demands that  $\{c_1, c_2, c_3, c_4\} \subseteq W$ .

et al., 2022, Theorem 5.3) and remains hard even when every voter approves at most 6 candidates, and each candidate is approved by at most 2 voters (Munagala et al., 2022a, Theorem 1). The verification problem is also hard to approximate to within a factor better than  $1 + 1/e$  (Munagala et al., 2022a, Theorem 2), though a logarithmic approximation algorithm exists (Munagala et al., 2022a, Theorem 3).

**More general settings.** We work in the model of approval-based committee elections. If non-approval preferences are allowed (such as cardinal additive valuations), the core may be empty (Fain et al., 2018, Appendix C; Peters et al., 2021, Example 2). For participatory budgeting applications, one can replace the cardinality constraint in the definition of a committee by a knapsack constraint. For this non-unit cost setting, approval votes have several interpretations (Rey and Maly, 2023, Section 3.4.2). One option is *cost utilities*, which measures a voter’s utility by the total cost of approved winning projects. For this utility model, the core may be empty (Maly, 2023). For *cardinality utilities*, where the voter’s utility is the number of approved winning projects, the non-emptiness of the core is an open question.

**Approximate core.** Core stability can be relaxed through multiplicative approximations, in two main ways. Say that a committee  $W$  is in the  $(\alpha, \beta)$ -core,  $\alpha, \beta \geq 1$ , if for every potential deviation  $T$ , we have  $|\{i \in N : |A_i \cap T| > \alpha \cdot |A_i \cap W|\}| < \beta \cdot |T| \cdot \frac{n}{k}$ . For  $\alpha = \beta = 1$ , this is the core; for  $\alpha > 1$ , every member of the blocking coalition must increase their utility by a factor of  $\alpha$ ; for  $\beta > 1$ , we require that blocking coalitions must be larger than usual by a factor of  $\beta$ .

Peters and Skowron (2020) show that PAV is in the  $(2, 1)$ -core, and that the Method of Equal Shares is in the  $(\log k, 1)$ -core (or a mild relaxation of that concept). Munagala et al. (2022b) show that the  $(9.27, 1)$ -core is non-empty even for general additive valuations. Fain et al. (2018, Appendix C) show that the  $(1 + \varepsilon, 1)$ -core is non-empty if it is additionally additively relaxed. Jiang et al. (2020) show that the  $(1, 16)$ -core is non-empty, via rounding a stable lottery (Cheng et al., 2020); they conjecture that at least the  $(1, 2)$ -core is always non-empty. A similar rounding technique has been used to analyze Condorcet winning sets (Charikar et al., 2024).

**Fractional models.** Analogs of core-stability have also been defined in fractional models. For example, Aziz et al. (2020) consider “fair mixing” in an approval-based model, where the output is a probability distribution over candidates (which can be interpreted as a division of a budget). They show that the rule maximizing Nash welfare (which is related to the PAV rule) satisfies core-stability. Fain et al. (2016) obtain the same result in a more general model with additive linear utilities. They also show that a core-stable outcome exists for fractional committees (which can be viewed as a probability distribution where each candidate receives mass at most  $1/k$ ) via Lindahl equilibrium which is known to exist from fixed-point theorems (Foley, 1970; Munagala et al., 2022b) and via convex programming (Kroer and Peters, 2025). Various weakenings of the core have also been studied in approval-based fair mixing and related models (see, e.g., Brandl et al., 2021; Suzuki and Vollen, 2024; Bei et al., 2025).

### 3 Preliminaries

Let  $C = \{c_1, \dots, c_m\}$  be a set of  $m$  candidates. Let  $k \in \{1, \dots, m\}$  be the committee size. A *committee* is a subset  $W \subseteq C$  of winning candidates with  $|W| = k$ .

Let  $\mathcal{A}$  denote the set of non-empty subsets of  $C$ , which we will refer to as *approval sets* or *ballots*. A *profile* is a map  $P : \mathcal{A} \rightarrow \mathbb{Q}_{\geq 0}$  with  $\sum_{A \in \mathcal{A}} P(A) = 1$ , where  $P(A)$  indicates the fraction of the voters that approve exactly the candidates in  $A$ . Given an approval set  $A \in \mathcal{A}$  and a

committee  $W$ , the *utility* of the committee for  $A$  is the number of approved committee members:  $u_A(W) = |A \cap W|$ .

A nonempty set  $T \subseteq C$  with  $|T| \leq k$  is called a *potential deviation*. Given a profile  $P$ , a committee  $W$  is *core stable* if for every potential deviation  $T$ , we have

$$\sum_{A \in \mathcal{A}: u_A(T) > u_A(W)} P(A) < \frac{|T|}{k}.$$

Otherwise,  $T$  is called a *deviation* (or a *successful deviation*) from  $W$ . The *core* is the set of committees that are core stable.

The  $n$ th *harmonic number* is  $H(n) = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n}$ . The *PAV score* assigned to a committee  $W$  by ballot  $A \in \mathcal{A}$  is

$$\text{PAV-score}_A(W) = H(u_A(W)).$$

Given a profile  $P$ , the *PAV score* of  $W$  under profile  $P$  is

$$\text{PAV-score}_P(W) = \sum_{A \in \mathcal{A}} P(A) \cdot \text{PAV-score}_A(W).$$

A committee is called a *global PAV committee* if it has the highest PAV score. The *PAV rule* selects all global PAV committees.

We will also be interested in local maxima of the PAV objective, i.e., committees that have a weakly higher PAV score than any committee obtained by performing a single swap. For a committee  $W$ ,  $x \in W$  and  $y \in C \setminus W$ , we write  $W_{xy} = W \setminus \{x\} \cup \{y\}$  for the committee obtained by replacing  $x$  with  $y$ . Given a profile  $P$  and a fixed committee  $W$ , we write

$$\Delta_{P,x,y} = \text{PAV-score}_P(W_{xy}) - \text{PAV-score}_P(W)$$

for the increase in PAV score resulting from this swap. For a ballot  $A$ , we define  $\Delta_{A,x,y}$  analogously. Then we say that  $W$  is a *local PAV committee* if  $\Delta_{P,x,y} \leq 0$  for all  $x$  and  $y$ . Note that every global PAV committee is also a local PAV committee.

The following lemma shows that a local PAV committee never admits deviations of certain kinds: neither disjoint deviations, nor deviations that contain only a single unelected candidate.

**Lemma 3.1** *Let  $W$  be a local PAV committee, and let  $T$  be a potential deviation. Suppose we have*

$$(i) T \cap W = \emptyset, \quad \text{or} \quad (ii) |T \setminus W| \leq 1.$$

*Then  $T$  is not a deviation from  $W$ .*

*Proof.* (i) is proved by Brill et al. (2022, Theorem 3.2 and Remark 3.4) using a swapping argument.

(ii) If  $T \setminus W = \emptyset$ , then  $T \subseteq W$ , and there are no approval ballots that strictly prefer  $T$  to  $W$ . If  $T \setminus W = \{c\}$ , then for every  $A \in \mathcal{A}$  with  $u_A(T) > u_A(W)$ , we have  $c \in A$ . Writing  $\ell = |T|$ , if  $T$  were a deviation, we would thus have a set  $S$  of ballots forming  $\ell/k$  of the profile, who all approve  $c \notin W$ , and who all have utility  $u_A(W) < u_A(T) \leq \ell$ . Thus, we have a violation of the EJ $R^+$  axiom of Brill and Peters (2023) which local PAV committees are known to satisfy.  $\square$

Note that Lemma 3.1(ii) implies that PAV satisfies the core when  $k = m - 1$  or  $k = m$ .

We recall the following well-known result about systems of linear inequalities, providing a certificate of infeasibility.

**Lemma 3.2** (Farkas' Lemma) *Let  $A \in \mathbb{Q}^{m \times n}$  be an  $m \times n$  matrix, and let  $b \in \mathbb{Q}^m$ . Then the following are equivalent.*

(i) There does not exist  $x \in \mathbb{Q}^n$  with  $Ax \leq b$ .

(ii) There exists an integer vector  $y \in \mathbb{Z}_{\geq 0}^m$  such that  $y^T b < 0$  and  $A^T y \geq 0$ .

Thus, by exhibiting the integer vector  $y$ , one can prove the infeasibility of the system  $Ax \leq b$ .

## 4 Small Committee Size

In this section, we discuss core-stable committees when the committee size  $k$  is small. We give existence results when  $k \leq 8$ , separately handling the cases  $k \leq 7$  and  $k = 8$ .

### 4.1 Committee size $k \leq 7$

For committee sizes up to 7, core-stable committees always exist because every local PAV committee is in the core. This establishes existence of core-stable committees, but also indicates that PAV rule is a very good rule for smaller committee sizes.<sup>3</sup> Like other proofs that PAV is proportional, our proof reasons about the change in PAV score caused by certain swaps. To establish a key inequality, the proof refers to the result of a computer enumeration of all possible ballot types, which can be reproduced using [Python code available on GitHub](#).

**Theorem 4.1** *When  $k \leq 7$ , every local PAV committee is in the core.*

*Proof.* Let  $W$  be a PAV committee with  $|W| = k \leq 7$ , and consider a potential deviation  $T$ . We need to show that  $T$  is not successful. Writing

$$s = \sum_{\substack{A \in \mathcal{A} \\ u_A(T) > u_A(W)}} P(A),$$

we need to show that  $s < |T|/k$ . We may assume that  $s > 0$ , since otherwise  $T$  is definitely not successful.

We now consider the following process: we remove some candidate  $x \in W \setminus T$  from the committee  $W$ , and replace it by some candidate  $y \in T \setminus W$ , and will estimate the total effect of these swaps. Because  $W$  is a local PAV committee, we have

$$\sum_{x \in W \setminus T} \sum_{y \in T \setminus W} \Delta_{P,x,y} \leq 0 \tag{1}$$

We can rewrite (1) by computing the contributions of each ballot to the differences in PAV score. Let  $A \in \mathcal{A}$ . Note that swapping in  $y$  for  $x$  either increases the utility  $u_A(W)$  by 1 point (if  $x \notin A$  but  $y \in A$ ), decreases it by 1 point (if  $x \in A$  but  $y \notin A$ ), or otherwise it stays the same. The number of  $(x, y)$  pairs leading to an increase is  $|(W \setminus T) \setminus A| \cdot |(T \setminus W) \cap A|$ ; the number of pairs leading to a decrease is  $|(W \setminus T) \cap A| \cdot |(T \setminus W) \setminus A|$ . Thus, from the point of view of the ballot  $A$ , the total difference in PAV score summed across all  $x$  and  $y$  becomes

$$\begin{aligned} \delta_A &:= \sum_{x \in W \setminus T} \sum_{y \in T \setminus W} \Delta_{A,x,y} \\ &= \frac{|(W \setminus T) \setminus A| \cdot |(T \setminus W) \cap A|}{u_A(W) + 1} - \frac{|(W \setminus T) \cap A| \cdot |(T \setminus W) \setminus A|}{u_A(W)}. \end{aligned}$$

<sup>3</sup>There are examples where the sequential Phragmén rule fails core (and even EJR) for  $k = 6$ , and where MES fails core for  $k = 7$ . These counterexamples work even for the party-approval setting (Brill et al., 2022), where each candidate can be placed in the committee several times. For Phragmén, take the 3-voter profile  $(ab, bc, ac)$ , where Phragmén can elect  $ababab$ , with  $T = \{c, c, c\}$  forming a deviation. For MES, take the 7-voter profile  $(ab, ac, ad, bcd, bcd, bcd, bcd)$ , where  $bbbbbaa$  is an outcome of MES, with  $T = \{c, c, c, d, d, d\}$  forming a deviation. (In these examples, there are other tied outcomes in the core, and I don't know if unique examples exist.)

Thus we can rewrite (1) as follows:

$$\sum_{A \in \mathcal{A}} P(A) \cdot \delta_A \leq 0 \quad (2)$$

We will now give lower bounds on the value of  $\delta_A$ .

First we give a trivial lower bound, valid for all  $A \in \mathcal{A}$ :

$$\begin{aligned} \delta_A &\geq -\frac{|(W \setminus T) \cap A| \cdot |(T \setminus W) \setminus A|}{u_A(W)} && \text{(dropping positive terms)} \\ &\geq -\frac{|W \cap A| \cdot |T \setminus W|}{u_A(W)} \\ &= -|T \setminus W|. && \text{(since } u_A(W) = |W \cap A|) \end{aligned}$$

Next, suppose  $A \in \mathcal{A}$  is a ballot with  $u_A(T) > u_A(W)$ , i.e.,  $|A \cap T| \geq |A \cap W| + 1$ . For such ballots, there exists a better lower bound for  $\delta_A$ . In particular, it is the case that

$$\delta_A > \left(\frac{k}{|T|} - 1\right) \cdot |T \setminus W|. \quad (3)$$

This can be shown by a **small exhaustive search** over all possible combinations of the quantities appearing in the definition of  $\delta_A$ . In particular, write

$$a = |(W \setminus T) \cap A|, \quad b = |(W \cap T) \cap A|, \quad c = |(T \setminus W) \cap A|.$$

Then we have  $\delta_A = \frac{(|W \setminus T| - a)c}{a + b + 1} - \frac{a(|T \setminus W| - c)}{a + b}$ , and one can check that this is always strictly larger than  $(\frac{k}{|T|} - 1) \cdot |T \setminus W|$  by trying all triples  $(a, b, c)$  with  $0 \leq a \leq |W \setminus T|$ ,  $0 \leq b \leq |W \cap T|$ , and  $0 \leq c \leq |T \setminus W|$  which satisfy  $b + c > a + b$  (which encodes that  $u_A(T) > u_A(W)$ ).<sup>4</sup>

Based on these bounds, we have

$$\begin{aligned} 0 &\geq \sum_{A \in \mathcal{A}} P(A) \cdot \delta_A && \text{(by (2))} \\ &> s \left( \left(\frac{k}{|T|} - 1\right) \cdot |T \setminus W| \right) + (1 - s)(-|T \setminus W|) && (s > 0) \\ &= |T \setminus W| \cdot \left( s \left(\frac{k}{|T|} - 1\right) - (1 - s) \right) \\ &= |T \setminus W| \cdot \left( s \frac{k}{|T|} - 1 \right). \end{aligned}$$

Thus, because  $|T \setminus W| > 0$ , we have  $0 > s \frac{k}{|T|} - 1$  and hence  $s < \frac{|T|}{k}$ , as desired.  $\square$

While it may not look like it, the result of **Theorem 4.1** was obtained by linear programming. Suppose that the result is false, so that there exists a profile  $P$  and a local PAV committee  $W$  such that some  $T$  is a successful deviation. Without loss of generality, there exists such an example with  $W = \{c_1, \dots, c_k\}$ . Note that  $P$  then forms a solution to the following system of linear inequalities, where we may assume that  $C = W \cup T$ :<sup>5</sup>

$$\begin{aligned} \sum_{A \in \mathcal{A}} P(A) &= 1 \\ \Delta_{P,x,y} &\leq 0 \quad \text{for all } x \in W \text{ and } y \in C \setminus W \\ \sum_{A \in \mathcal{A}: u_A(T) > u_A(W)} P(A) &\geq \frac{|T|}{k} \\ P(A) &\geq 0 \quad \text{for all } A \in \mathcal{A} \end{aligned} \quad (4)$$

<sup>4</sup>Note that none of  $a, b, c$  depend on  $m$ , so the search is finite and the proof works independently of the number of candidates.

<sup>5</sup>We may make this assumption because a counterexample on a larger  $C$  remains a counterexample when restricted to  $W \cup T$ , because a local PAV committee remains a local PAV committee after deleting candidates outside the committee.

Thus, [Theorem 4.1](#) is proven if the system (4) does *not* have a feasible solution, for all potential deviations  $T$ . By Farkas' lemma, that means that for every  $T$ , there exist  $\alpha \in \mathbb{R}$ ,  $(\beta_{xy})_{xy} \geq 0$ ,  $\gamma \geq 0$  satisfying

$$\begin{aligned} \alpha - \frac{|T|}{k}\gamma &< 0 \\ \alpha + \sum_{x \in W} \sum_{y \notin W} \Delta_{A,x,y} \cdot \beta_{xy} - \gamma &\geq 0 && \text{for all } A \in \mathcal{A} \text{ with } u_A(T) > u_A(W) \\ \alpha + \sum_{x \in W} \sum_{y \notin W} \Delta_{A,x,y} \cdot \beta_{xy} &\geq 0 && \text{for all } A \in \mathcal{A} \text{ with } u_A(T) \leq u_A(W) \end{aligned}$$

In fact, the proof of [Theorem 4.1](#) simply constructs such a certificate solution for every  $T$ , where  $\alpha = |T \setminus W|$  and  $\beta_{xy} = 1$  whenever  $x \in W \setminus T$  and  $y \in T \setminus W$ , and  $\beta_{xy} = 0$  otherwise.

Due to the following remark, it is possible to compute a core-stable outcome in  $O(m^2n)$  time whenever  $k \leq 7$ .

**Remark 4.2** Let  $k \leq 7$  and  $\varepsilon = 0.1/k^2$ . By solving linear programs [[GitHub](#)], one can check that every committee that is  $\varepsilon$ -local-swap-stable (i.e.,  $\Delta_{P,x,y} \leq \varepsilon$  for all  $x$  and  $y$ ) is in the core. An  $\varepsilon$ -local-swap-stable and thus a core-stable committee can be found by performing  $O(k^2 \ln k) = O(1)$  many  $\varepsilon$ -improving swaps (see [Aziz et al., 2018](#), Proposition 1), each of which takes  $O(m^2n)$  time to find. It turns out that for  $\varepsilon = 1/k^2$ , it is not the case that every  $\varepsilon$ -local-swap-stable committee is in the core, even though this value of  $\varepsilon$  is enough to ensure that the committee satisfies EJR ([Aziz et al., 2018](#), Theorem 1). For example, in the profile with  $P(\{a, b\}) = P(\{a, c\}) = 0.25$  and  $P(\{d, e, f, g, h\}) = 0.5$ , for  $k = 6$ , the committee  $\{a, d, e, f, g, h\}$  fails the core due to  $T = \{a, b, c\}$ , but it is  $1/40$ -local-swap-stable, and  $1/40 < 1/36 = 1/k^2$ .

## 4.2 Committee size $k = 8$

[Theorem 4.1](#) does not hold for  $k = 8$ : There are profiles where some local (and even global) PAV committee is not in the core.

**Example 4.3** (PAV may fail core for  $k = 8$ ) Consider an instance with 4 voters,  $v_1$  approving  $\{c_1, c_2, c_3\}$ , and  $v_2$  approving  $\{c_1, c_2, c_4\}$ , and the other 2 voters approving  $\{c_5, c_6, c_7, c_8, c_9, c_{10}\}$ . This profile is depicted below, where each voter approves the candidates above the voter's label.

				$c_{10}$
				$c_9$
				$c_8$
	$c_3$	$c_4$		$c_7$
	$c_2$			$c_6$
	$c_1$			$c_5$
$v_1$	$v_2$	$v_3$	$v_4$	

On this profile,  $W = \{c_1, c_2, c_5, c_6, c_7, c_8, c_9, c_{10}\}$  is a global PAV committee (indicated in blue in the picture). However,  $W$  is not in the core: consider  $T = \{c_1, c_2, c_3, c_4\}$ , which has support from  $\frac{1}{2}$  of the voters, and  $|T|/k = \frac{1}{2}$ .  $\square$

Note, however, that in [Example 4.3](#), there is more than one global PAV committee. In particular,  $W' = \{c_1, c_2, c_3, c_5, c_6, c_7, c_8, c_9\}$  (obtained by removing  $c_{10}$  and adding  $c_3$ ) is also a global PAV committee and it is in the core.

It turns out that [Example 4.3](#) is essentially the only example where a PAV committee fails to be core-stable for  $k = 8$ , as all such examples share the same structure.

**Lemma 4.4** *Let  $P$  be a profile and suppose that  $W$  with  $|W| = 8$  is a local PAV committee that is not in the core due to objection  $T$ . Then there exist distinct  $a, b \in W$  and distinct  $x, y \in C \setminus W$  such that  $T = \{a, b, x, y\}$ . In addition,*

- (i) *one quarter of the voters submit ballots  $A$  such that  $A \cap (W \cup T) = \{a, b, x\}$  and another quarter submit ballots with  $A \cap (W \cup T) = \{a, b, y\}$ ,*
- (ii) *the remaining half of the voters submit ballots that are disjoint from  $T$ , and*
- (iii) *the PAV score of  $W$  is reduced by exactly  $1/12$  if any one member of  $W \setminus \{a, b\}$  is removed.*

*Proof.* We first check that if  $W$  is not in the core, then any core objection must use a  $T$  with  $|T| = 4$  and  $|W \cap T| = 2$ . This can be deduced using the linear programming approach behind [Theorem 4.1](#); by iterating through all possible  $T$ , we find that the system (4) has a solution only for  $T$  satisfying the condition in the theorem statement. Alternatively, one can check [\[GitHub\]](#) that the inequality (3) is only violated for such  $T$ ; thus for other  $T$  the proof of [Theorem 4.1](#) goes through.

Now fix such a  $T = \{a, b, x, y\}$ . Assume that there exists a profile  $P$  where  $W$  is a local PAV committee with successful deviation  $T$  but that violates any of the conditions (i)–(iii). Then if we delete all candidates outside  $W \cup T$  from the profile, it would still fail (i)–(iii). Thus, for purposes of making the following linear programs finite, we may assume that  $C = W \cup T$  (so  $|C| = 10$ ).

To prove (i), we solve the following four linear programs:

$$\begin{aligned} & \text{maximize } P(\{a, b, x\}) \text{ subject to } P \text{ satisfying (4)} \\ & \text{minimize } P(\{a, b, x\}) \text{ subject to } P \text{ satisfying (4)} \\ & \text{maximize } P(\{a, b, y\}) \text{ subject to } P \text{ satisfying (4)} \\ & \text{minimize } P(\{a, b, y\}) \text{ subject to } P \text{ satisfying (4)} \end{aligned}$$

The optimal solutions to all these programs is  $\frac{1}{4}$ .

To prove (ii), iterate through all ballots  $A \in \mathcal{A}$  with  $A \cap T \neq \emptyset$ , except for  $\{a, b, x\}$  and  $\{a, b, y\}$ . For each of these ballots, solve the following linear program:

$$\text{maximize } P(A) \text{ subject to } P \text{ satisfying (4)}$$

For each such  $A$ , the optimal solution of the program is 0.

To prove (iii), iterate through all  $c \in W \setminus \{a, b\}$  and solve the following linear programs:

$$\begin{aligned} & \text{maximize } \text{PAV-score}_P(W \setminus \{c\}) - \text{PAV-score}_P(W) \text{ subject to } P \text{ satisfying (4)} \\ & \text{minimize } \text{PAV-score}_P(W \setminus \{c\}) - \text{PAV-score}_P(W) \text{ subject to } P \text{ satisfying (4)} \end{aligned}$$

The optimal solutions to these two programs are  $-1/12$ . □

The claims made in this proof about the optimal values of the various linear programs can be certified by exhibiting solutions to the dual programs. These certificates (using exact fractions, not floating point numbers) are [available on GitHub](#), together with a script checking their validity without using a solver.

As we discussed, [Example 4.3](#) shows an example of a global PAV committee that is not core-stable, but there are other global PAV committees for the same profile that are core-stable. Thanks to [Lemma 4.4](#), we deduce that the same holds for *all* counterexamples. Hence, for every instance, at least one global PAV committee is in the core, and thus the core is always non-empty for  $k = 8$ .



---

**Algorithm 1** Recursive PAV rule

---

**Input:** A profile  $P$  and a committee size  $k$   
**Output:** A committee  $W$   
 $\mathcal{A}' \leftarrow \mathcal{A}$ , set of active ballots  
 $F \leftarrow \emptyset$ , set of *fixed* candidates  
**while** true **do**  
    If  $|F| > k$ , the algorithm **fails**  
     $W \leftarrow$  any committee locally maximizing the PAV score  
        w.r.t. the ballots in  $\mathcal{A}'$  and subject to  $F \subseteq W$   
    **if** there exists a successful deviation  $T$  from  $W$  **then**  
         $F \leftarrow F \cup T$   
         $\mathcal{A}' \leftarrow \mathcal{A}' \setminus \{A \in \mathcal{A} : u_A(T) > u_A(W)\}$   
    **else**  
        **return**  $W$

---

PAV committee with respect to the remaining voters, but subject to the constraint that  $T \subseteq W$ . It then checks if the result is in the core; if not, it adds additional constraints until it reaches a core-stable committee. This rule is formally described using pseudocode in [Algorithm 1](#).

For example, in the profile of [Example 4.3](#), PAV selects the committee  $W$  indicated there in blue (among other tied committees). This committee is blocked by  $T = \{c_1, c_2, c_3, c_4\}$ . Thus, the recursive PAV rule would now fix all members of  $T$  as winners, and maximize the PAV-score with respect to voters  $v_3$  and  $v_4$ , obtaining the committee  $W^* = \{c_1, c_2, c_3, c_4, c_5, c_6, c_7, c_8\}$  (among other tied committees). This committee is in the core, so the rule terminates. Note that  $W^*$  is not itself selected by PAV, though as we saw previously, there do exist other (global) PAV committees in the core in [Example 4.3](#).

This method is reminiscent of the Greedy Cohesive Rule ([Peters et al., 2021](#)), which similarly repeatedly patches a committee until it satisfies the representation axiom FJR.

## 5.1 Analysis of the Method

Fix a number of candidates  $m$  and a committee size  $k$ .

A list  $(W_1, T_1), (W_2, T_2), \dots, (W_r, T_r)$  is called a *potential history* if for each  $t \in [r]$ , we have that  $W_t$  is a committee,  $T_t$  is a potential deviation, and  $T_1 \cup \dots \cup T_{t-1} \subseteq W_t$ .

**Definition 5.1** A potential history  $(W_1, T_1), \dots, (W_r, T_r)$  is a *history* if there exists a profile  $P$  such that for each  $t \in [r]$  we have that  $T_t$  is a *successful* deviation from  $W_t$ , and that for all  $x \in W \setminus (T_1 \cup \dots \cup T_{t-1})$  and  $y \in C \setminus W$ , we have

$$\sum_{A \in \mathcal{A}_t} P(A) \cdot \text{PAV-score}_A(W_t) \geq \sum_{A \in \mathcal{A}_t} P(A) \cdot \text{PAV-score}_A(W_{xy})$$

where  $\mathcal{A}_t = \{A \in \mathcal{A} : u_A(T_s) \leq u_A(W_s) \text{ for } s \in \{1, \dots, t-1\}\}$  is the set of “active” ballots. That is,  $W_t$  locally maximizes the PAV score among all committees that include all prior deviations, taking only those voters into account that did not participate in prior deviations.

Thus, a history provides a trace of the execution of [Algorithm 1](#) for some profile. The following result states that it is enough to analyze the set of histories to determine if [Algorithm 1](#) always terminates with a core-stable committee.

**Proposition 5.2** *Suppose that for every history  $(W_1, T_1), \dots, (W_r, T_r)$ , we have  $|T_1| + \dots + |T_r| \leq k$ . Then a core-stable committee always exists for  $m$  and  $k$ .*

---

**Algorithm 2** Finding all histories

---

**Input:** Number  $m$  of candidates and a committee size  $k$   
**Output:** A collection of all histories and Farkas certificates  
 $\mathcal{H}_0 \leftarrow \{\emptyset\}$ , the empty history  
**for**  $t = 1, 2, \dots$  **do**  
    **for all**  $H \in \mathcal{H}_{t-1}$  **do**  
        **for all** potential continuations  $(W_t, T_t)$  **do**  
            **if**  $(W_t, T_t)$  is not canonical with respect to  $H$  **then**  
                **continue**  
                Set  $H' \leftarrow H + (W_t, T_t)$   
                Solve LP to check if  $H'$  is a history  
                **if yes**, add  $H'$  to  $\mathcal{H}_t$   
                **if no**, generate a Farkas certificate  
    **if**  $\mathcal{H}_t = \emptyset$  **then**  
        **break**

---

*Proof.* Let  $P$  be a profile, and run [Algorithm 1](#) on it. By the assumption, in each iteration,  $|F| \leq |T_1| + \dots + |T_r| \leq k$ , so the algorithm does not fail. By the if-clause, if the algorithm terminates, it returns a committee that is core-stable. Thus, it suffices to show that the algorithm terminates.

Note that after each iteration of the algorithm, it either terminates or it has found a successful deviation. Suppose iteration  $r$  has ended without the algorithm terminating. The sequence of committees and deviations  $(W_1, T_1), \dots, (W_r, T_r)$  identified by the algorithm up to iteration  $r$  forms a history. Since  $|T_t| \geq 1$  for all  $t$ , it follows from  $|T_1| + \dots + |T_r| \leq k$  that  $r \leq k$ . So it must terminate after at most  $k + 1$  iterations.  $\square$

Thus, to prove the existence of core-stable committees, it suffices to enumerate all histories and check that they fulfil the condition of [Proposition 5.2](#). Given a potential history, one can check using an LP solver whether it is a history by checking whether the system of linear inequalities in [Definition 5.1](#) has a solution. This way, we can compute the set of histories using a standard breadth-first search, as shown in [Algorithm 2](#). A key insight to speed up the search is that we may break symmetries and only need to consider “canonical” histories in our enumeration. For example, we may assume without loss of generality that  $W_1$ , the first committee of the history, is  $\{c_1, \dots, c_k\}$ . Similarly, we do not need to consider all potential deviations  $T_1$ : given our choice of  $W_1$ , the candidates in  $W_1$  are indistinguishable to each other, as are the candidates in  $C \setminus W_1$ , and thus it suffices to take one deviation for each possible combination of the sizes of  $|T_1 \cap W_1|$  and of  $|T_1 \cap (C \setminus W_1)|$ . Similar symmetry-breaking conditions apply for later steps.<sup>6</sup>

For example, for  $m = 15$  and  $k = 13$ , [Algorithm 2](#) produces the following set of (canonical)

---

<sup>6</sup>Abstractly speaking, if an algorithm has identified sets  $A_1, \dots, A_s \subseteq C$  thus far (where in the present application, these sets are  $W_t$ 's and  $T_t$ 's), we can define an equivalence relation with  $a \sim b$  if and only if for each  $t \in [s]$ , either  $a, b \in A_t$  or  $a, b \in C \setminus A_t$ . Then two possibilities  $A_{s+1}$  and  $A'_{s+1}$  for the next set in the sequence are indistinguishable if for every equivalence class of  $\sim$ , the two possibilities contain the same number of elements from that equivalence class. A *canonical* choice for the next set would choose the lexicographically first elements from each equivalence class.

$k =$	9	10	11	12	13
number of canonical histories	7	11	15	20	15
number of Farkas witnesses	20 476	25 313	18 567	43 140	6 877
time for checking Farkas (s)	2 648	3 301	2 087	5 857	725

**Table 1** Statistics about the histories for  $m = 15$ .

histories, where we write  $W_1 = \{c_1, \dots, c_{13}\}$  and  $W_2 = \{c_1, \dots, c_{11}, c_{14}, c_{15}\}$ .

$\emptyset$ , the empty history  
 $(W_1, \{c_1, c_2, c_3, c_4, c_5, c_6, c_7, c_8, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_2, c_3, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_2, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_2, c_3, c_4, c_5, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_2, c_3, c_4, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_2, c_3, c_4, c_5, c_6, c_7, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_2, c_3, c_4, c_5, c_6, c_{14}, c_{15}\})$   
 $(W_1, \{c_1, c_{14}, c_{15}\}), (W_2, \{c_2, c_{12}, c_{13}\})$   
 $(W_1, \{c_1, c_{14}, c_{15}\}), (W_2, \{c_2, c_3, c_{12}, c_{13}\})$   
 $(W_1, \{c_1, c_2, c_3, c_{14}, c_{15}\}), (W_2, \{c_4, c_5, c_{12}, c_{13}\})$   
 $(W_1, \{c_1, c_2, c_{14}, c_{15}\}), (W_2, \{c_3, c_{12}, c_{13}\})$   
 $(W_1, \{c_1, c_2, c_{14}, c_{15}\}), (W_2, \{c_3, c_4, c_{12}, c_{13}\})$   
 $(W_1, \{c_1, c_2, c_{14}, c_{15}\}), (W_2, \{c_3, c_4, c_5, c_{12}, c_{13}\})$

By running [Algorithm 2](#) for  $m = 15$  and  $k = 9, \dots, 13$ , we obtain the following result. (Note that existence for  $m = 15$  implies existence for all  $m \leq 15$ .)

**Theorem 5.3** *If  $m \leq 15$ , a core-stable committee exists.*

The computations establishing [Theorem 5.3](#) can be verified based on Farkas certificates: the [code repository](#) includes, for each history and each possible extension of the history that induces an infeasible system of linear inequalities, a Farkas witness. Each witness is a list of about  $t \cdot k \cdot (m - k)$  integers, where  $t$  is the length of the history, corresponding to the constraints in [Definition 5.1](#), and verifying the correctness of the witness requires checking about  $2^m$  inequalities. In total, there are 114 373 witnesses (taking 125 MB) and verifying their validity using a simple script [[GitHub](#)] performing exact fractional computations (without calling a solver) takes about 4 hours on 8 cores (see [Table 1](#)).

The recursive PAV rule fails for  $m = 16$ ,  $k \in \{10, 11\}$ . For  $m = 16$ ,  $k = 10$ , the smallest failure example I have found has 40 448 550 voters, though the ILP for minimizing this number did not converge within a reasonable amount of time. The example is [available online](#).<sup>7</sup> The recursive PAV rule *does* work for  $m = 16$ ,  $k \in \{9, 12, 13, 14\}$ , and it is plausible that it can be fixed *ad hoc* for  $k \in \{10, 11\}$ , so it is likely that the core continues to exist for  $m = 16$ .

<sup>7</sup>The history that witnesses this failure is the following:  $(\{c_0, c_1, c_2, c_3, c_4, c_5, c_6, c_7, c_8, c_9\}, \{c_0, c_{10}, c_{11}\}), (\{c_0, c_1, c_2, c_3, c_4, c_5, c_6, c_{10}, c_{11}, c_{12}\}, \{c_{13}, c_{14}, c_{15}\}), (\{c_0, c_1, c_2, c_3, c_{10}, c_{11}, c_{12}, c_{13}, c_{14}, c_{15}\}, \{c_4, c_5, c_6, c_7, c_8\})$ .



(MES) (Peters and Skowron, 2020) or the sequential Phragmén method (Phragmén, 1894; Janson, 2016) do not admit the same kind of linear formulations (because they would require multiplying variables corresponding to ballot frequencies with variables corresponding to  $\rho$ -values or to loads). The lack of such a linear formulation can be formally established using the techniques of Xia (2025). In part because computer search is difficult for these rules, to the best of my knowledge, there is no known profile where both PAV and MES fail core-stability simultaneously. I am also not aware of any example where the rule that maximizes the PAV score among all *priceable* committees (Peters and Skowron, 2020) fails core-stability.

Maly (2023) presents an example in the participatory budgeting setting with cost utilities where the core is empty. That example uses only 3 voters. It would be interesting to see if computer-aided methods could establish that for committee elections, the core is always non-empty for  $n = 3$  voters. Note that in this case, candidates can be specified via the set of voters that approve the candidate, so there are only  $2^3$  different types of candidates, and thus a profile can be specified via variables that indicate how many candidates of each type exist.

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